

Fig. 1

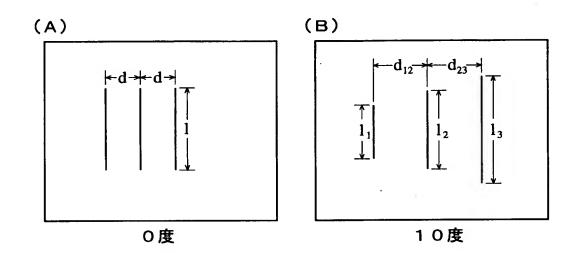
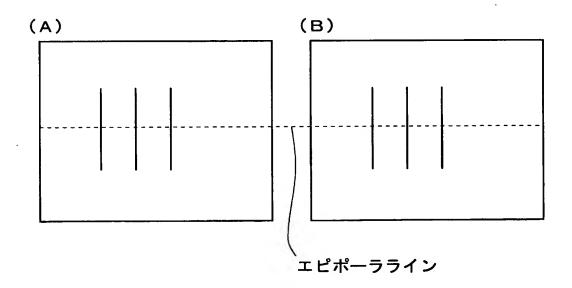
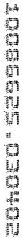
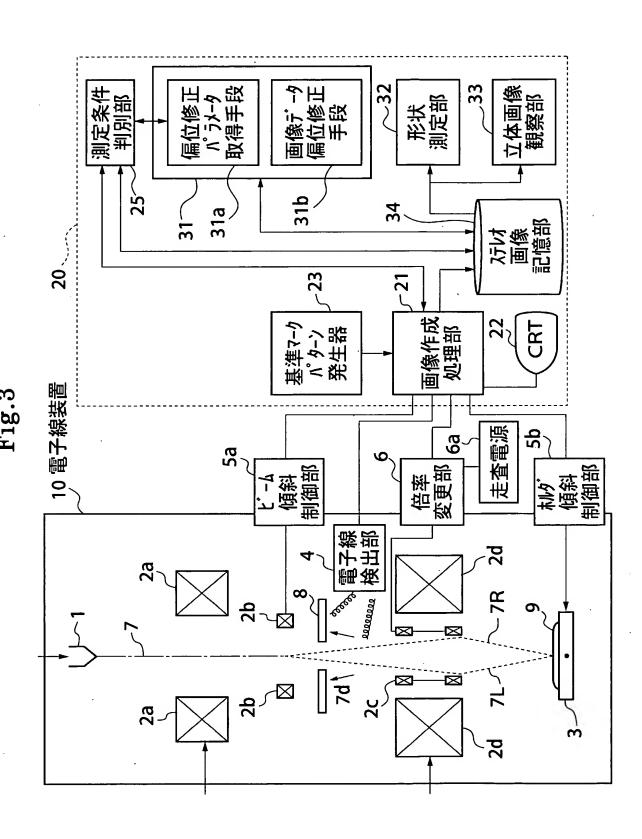


Fig. 2



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Fig. 4 (A) - 9a 40 (B) 40b 40a (C) 40b

Fig. 5

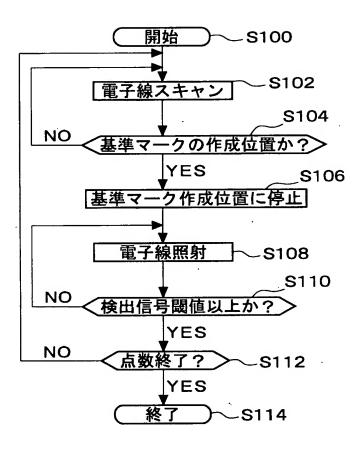


Fig. 6

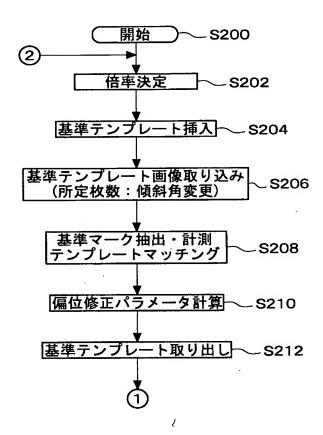
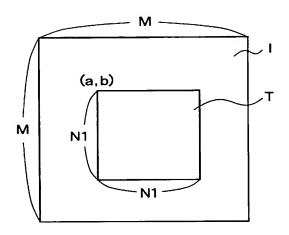


Fig. 7



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Fig. 8

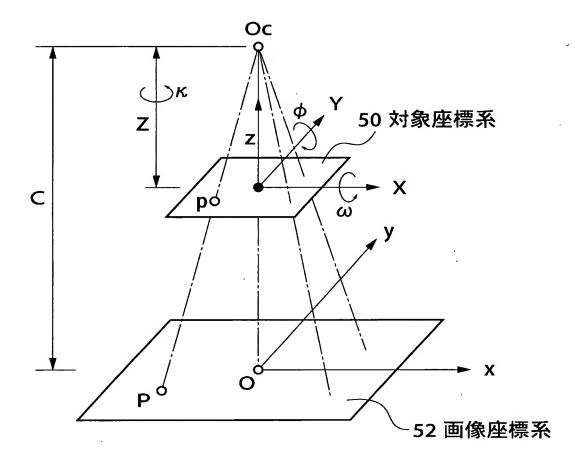


Fig. 9

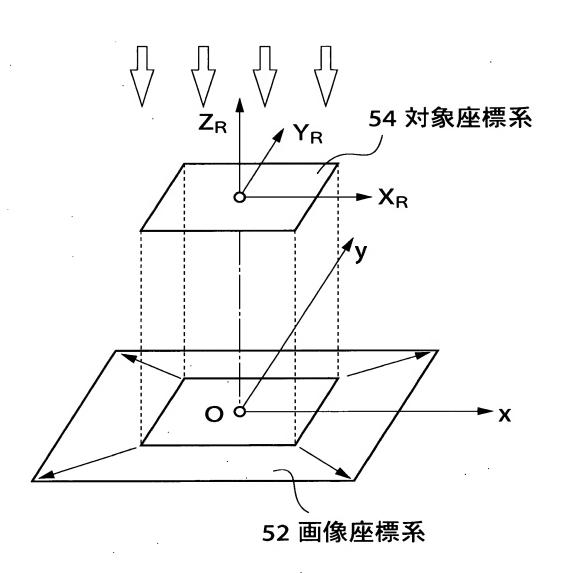


Fig. 10

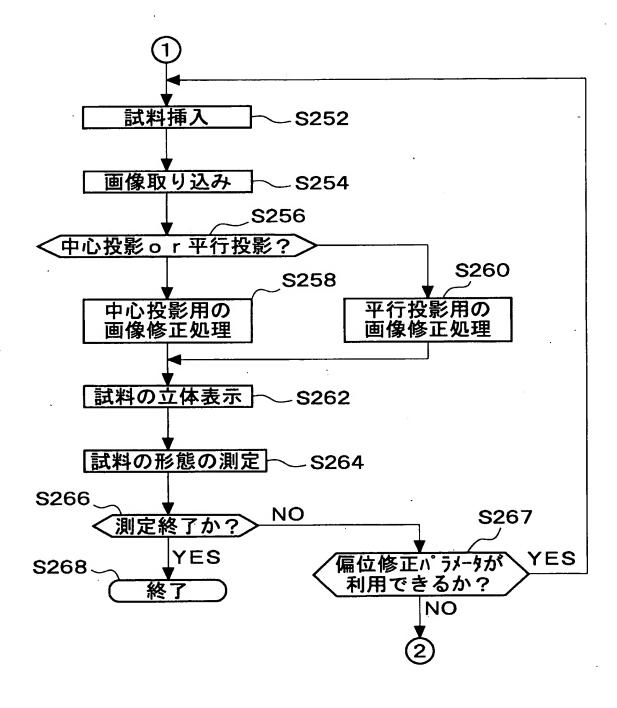
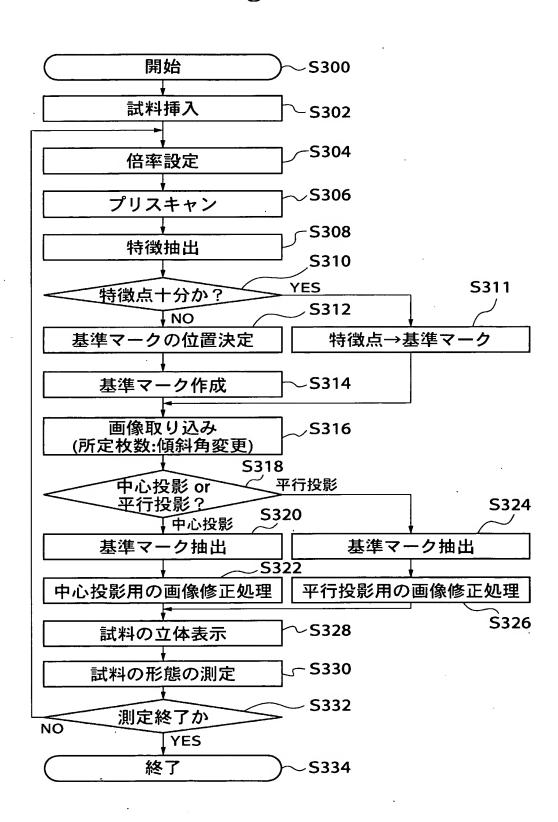


Fig. 11



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Fig. 12

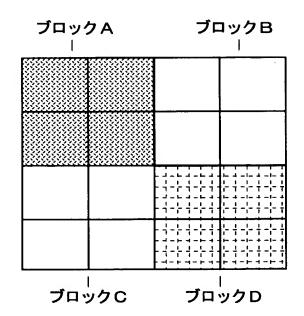
(A) ラプラシアンオペレータ

0	<b>–</b> 1	0
<b>—</b> 1	5	<b>— 1</b>
0	<b>— 1</b>	0

(B)線検出が゚レータ

-1/2	1	-1/2
-1/2	1	-1/2
-1/2	1	-1/2

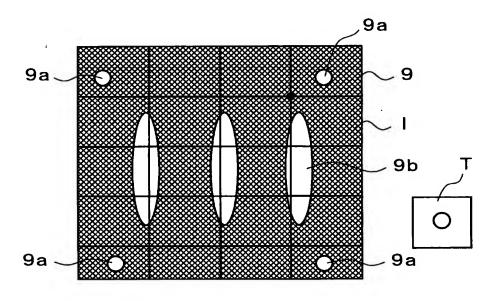
Fig. 13



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Fig. 14





画象データ 偏位修正 手段 偏位修正 パラメータ 立体画像 観察部 取得手段 形状 巡定部 25 31b 31a がな 画像 記憶部 画像作成 処理部 パ ターン 発生器 CRT 10 電子線装置 走査電源 **2**p 6a C - 7 傾斜 (御部 伯 黎 更部 制御部 亚 電子線檢出部



